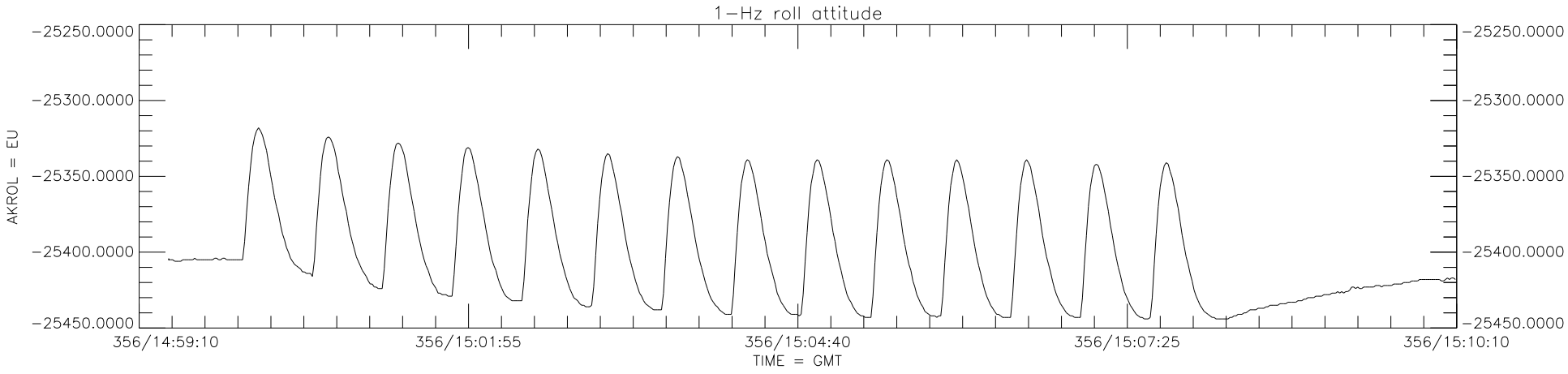
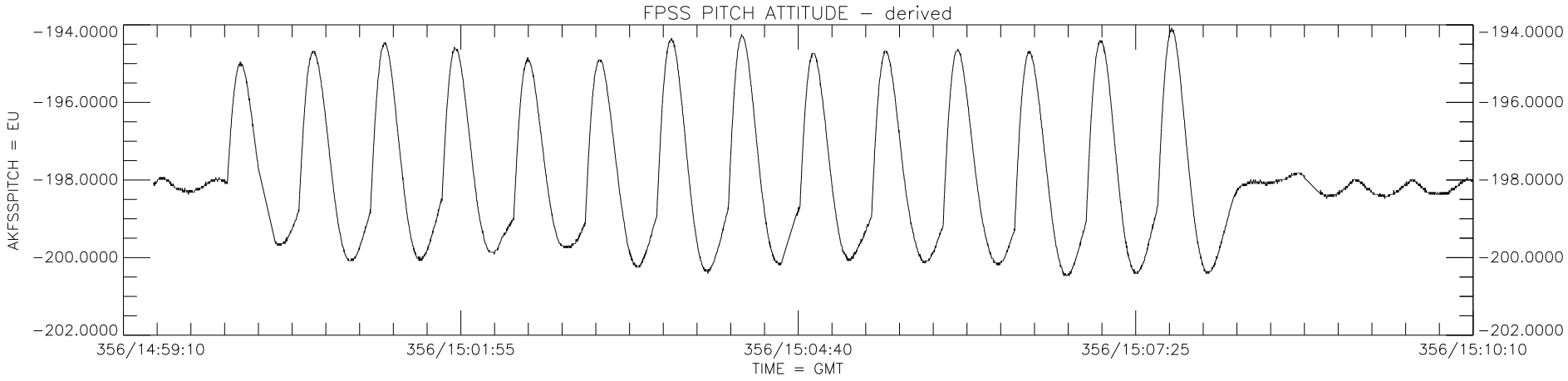
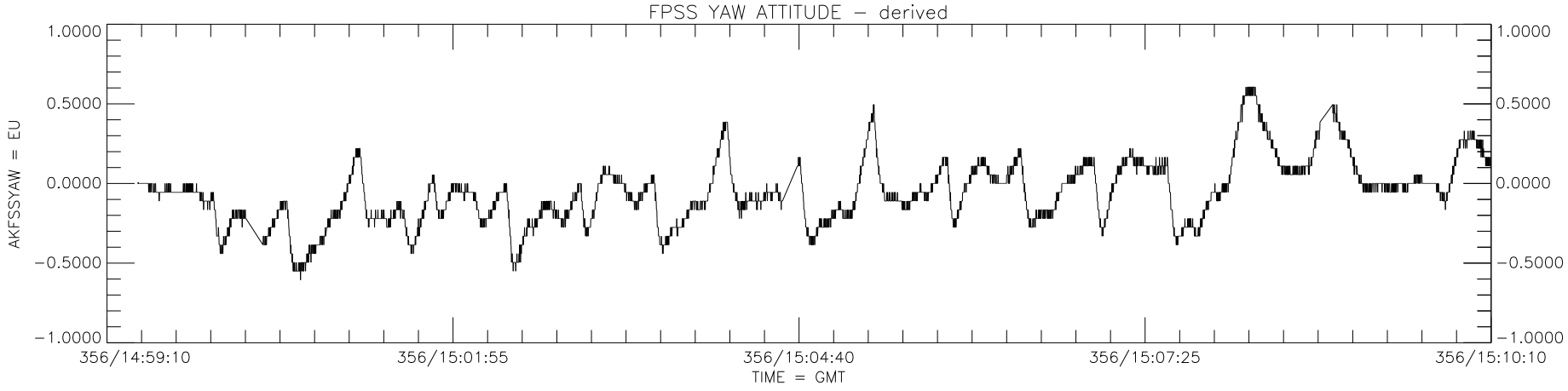

1−Hz roll attitude
AKROL = EU
−25250.0000
−25300.0000
−25350.0000
−25400.0000
−25450.0000
356/14:59:10
356/15:01:55
356/15:04:40
356/15:07:25
356/15:10:10
TIME = GMT


FPSS PITCH ATTITUDE − derived
AKFSSPITCH = EU
−194.0000
−196.0000
−198.0000
−200.0000
−202.0000
356/14:59:10
356/15:01:55
356/15:04:40
356/15:07:25
356/15:10:10
TIME = GMT


FPSS YAW ATTITUDE − derived
AKFSSYAW = EU
1.0000
0.5000
0.0000
−0.5000
−1.0000
356/14:59:10
356/15:01:55
356/15:04:40
356/15:07:25
356/15:10:10
TIME = GMT